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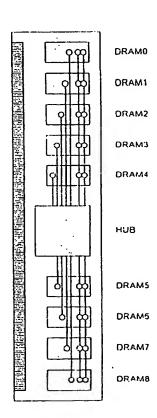
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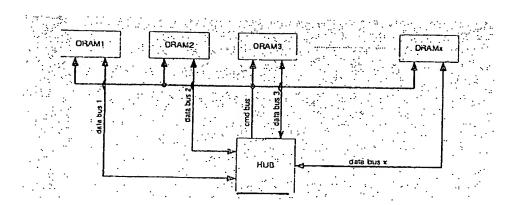
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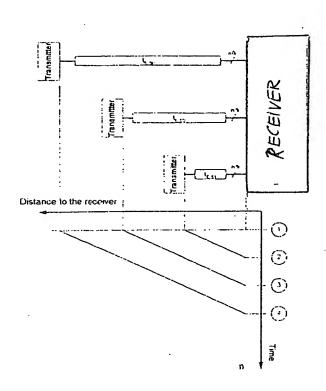
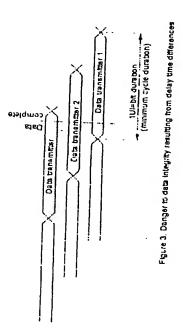
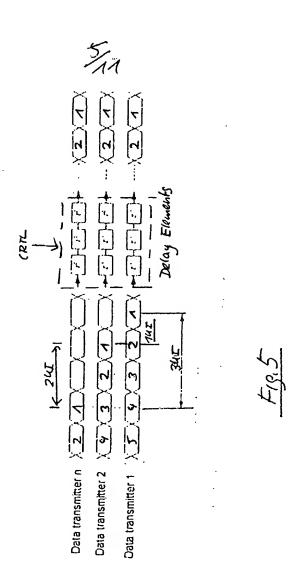


Fig3





Title: METHOD FOR MEASURING AND COMPENSATING SKEWS OF DATA TRANSMISSION LINE

TRANSMISSION LINE
Applicant(s): Paul George Lindt
Atty. Docket No.: 1406/142/2

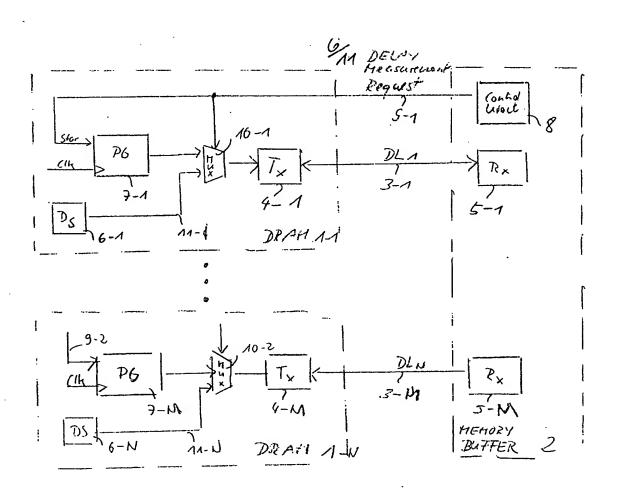


Fig6

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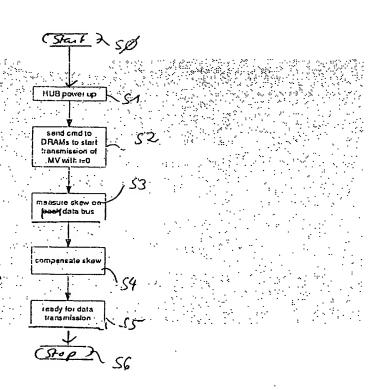
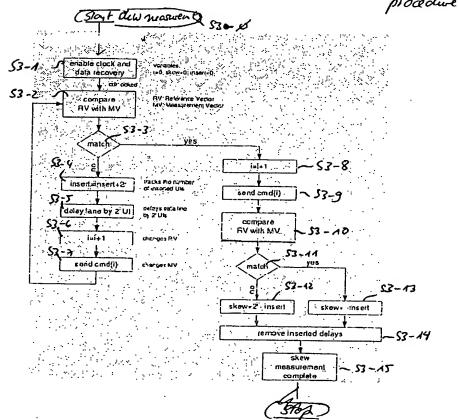


Fig 7

Title: METHOD FOR MEASURING AND COMPENSATING SKEWS OF DATA TRANSMISSION LINE Applicant(s): Paul George Lindt

Atty. Docket No.: 1406/142/2

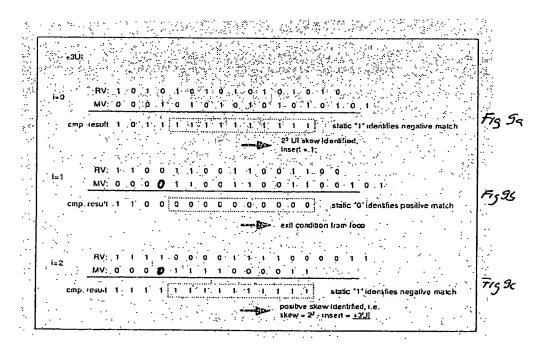
Steen masswement procedure (53)



Title: METHOD FOR MEASURING AND COMPENSATING SKEWS OF DATA TRANSMISSION LINE Applicant(s): Paul George Lindt

Applicant(s): Paul George Lindt Atty. Docket No.: 1406/142/2

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F19.9

	-
PV 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1	
MV: 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1	Fig 104
cmp. result 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	
20 UI skew identified	_
Insert - da	
RV: 42 1100111001110011100	
1 MV: 0 1: 4 0 0 1 1 0 0 0 1 1 0 0 0 1 1 0 0 0 1 1 1 0 0 1 1 1 0 0 1 1 1 0 0 1 1 1 0 0 1 1	,,,
cmp. result 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	F15 105
21 Ul skew identified.	•
insert = 3;	
RV: 1 1 1 1 0 0 0 0 1 1 1 1 0 0 0 0	
in2 MV: 0 0 0 1 1 1 1 0 0 0 0 1 1 1 1 0 0 0 0	
	715 10c
cmp. result. 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1)
exit condition from loop	
AV:	
MV: 6 3 6 1 4 1 1 1 1 1 1 0 0 0 0 0 0 0 0 0 1 1 1	19101
cmp. result 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 static "0" identifies positive match	J
negative skew identified, i.e.	
256M = 11130d = 301	
•	

F19.10

Title: METHOD FOR MEASURING AND COMPENSATING SKEWS OF DATA TRANSMISSION LINE

Applicant(s): Paul George Lindt Atty. Docket No.: 1406/142/2

